



MODEL





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Dimension (LxWxH)	1180x700x390 mm	950x500x350 mm
Weight	12.8KG (without battery)	6Kg (without battery)
Payload	mini Single-frequency Echo Sounder (default), plus ADCP, Sub-bottom Profiler, Side Scan Sonar, Multi-beam Echo Sounder, etc.	mini Single-frequency Echo Sounder (default) only

Material Nano carbon fiber polymer composite

IP Rating

Gentle breeze, smooth wavelet Wind-wave Resistance

Nano SIM card slot available Telecom Interface

Remote control operating distance

Modular, plug-in System Assembly

ELECTRICAL

Video Communication 4G telecom & network bridge

High-efficiency culvert long-life brushless motor Motor Engine

Typical 850W each Motor Power

Portable and detachable high-performance ternary Lithium battery, 33V, 45000mAh Battery

Endurance

PERFORMANCE

Propulsion Electric drive

7m/s max. Cruise Speed

Steering engine free, differential steering, reversible Steering Mode

Built in, highly integrated with transducer, fully automatic operation after power connection. Operating frequency 200kHz, beam angle 5°, sounding angle 0.15-100m (upgradeable). Default Echo Sounder

single battery, long-life option available)

Operating frequency - high frequency≥200kHz, low frequency≤20kHz; beam angle – high frequency≤5° Optional Echo Sounder

low frequency≤20°; sounding angle – high frequency 0.15-300m, low frequency 0.5-600m

N/A

POSITIONING

IMU Performance

Dual antenna, pre-installed in front and rear individually **GNSS Antenna**

GNSS Constellation 1598 channels, support GPS, Glonass, Galileo, Beidou-2, Beidou-3, Beidou-PPP, IRNSS, QZSS, SBAS, L-band, etc.

Single-point Positioning Accuracy

 $H \le 1.5 m, V \le 2.5 m$

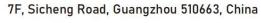
Heading accuracy 0.15°@1m baseline, orientation accuracy 0.25°@1m baseline

< 10cm, optional Beidou-PPP Accuracy

H:±(8+106 xD)mmV:±(15+106xD)mmD-Baseline length (Unit: mm) **RTK Accuracy**

IMU Onboard Supports GNSS-inertial, 1PPS, IMU refresh rate 200Hz max.

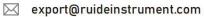






Note: all information above is subject to change without any prior notice.

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AQUAM20/M10

Built for Marine Unmanned







- 1 Dual Ducted Propeller double propulsion system for powerful cruise
- 2 Double-decker Trimaran smart structural design for reliable and stable cruise
- 3 Rear GNSS Antenna works with inbuilt GNSS for precise positioning
- 4 Auto-pilot System excels in unmanned operation
- 5 Network Bridge Antenna Port talks with remote controller to transfer data
- 6 Specialized Moon Pool ready to fit a variety of payloads like ADCP, multi-beam
- 7 4G Telecom Antenna Port equipped for RTK corrections and vessel remote control
- 8 Radio Datalink Antenna Port communicates with base station for RTK corrections
- 9 Battery Compartment endurance around 5 hours in auto-pilot mode
- 10 Power Display Panel for direct voltage value reading
- 11 Device Power Switch one-key quick start
- 12 Recharge Port standalone or direct onboard charging, optional
- 13 Mini Echo Sounder F18S single frequency, built in as default
- 14 Double-sided Guide Light blinks in green against mission safety
- 15 World-famous 360° Camera provides pano view during missions
- 16 Millimeter Microwave Radar designed for obstacle avoidance
- 17 Front GNSS Antenna provides stable heading info for auto-pilot
- 18 Remote Control Unit mission planning and control all in one



SOFTWARE

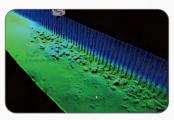
APPLICATIONS



Auto-pilot



Satellite Map



Multi-beam Mapping



Obstacle Detection



Dredging Works



Underwater Bathymetry



River Measurement





Hydrology Investigation

CONFIGURATION



Note: just take M20 for example above.





